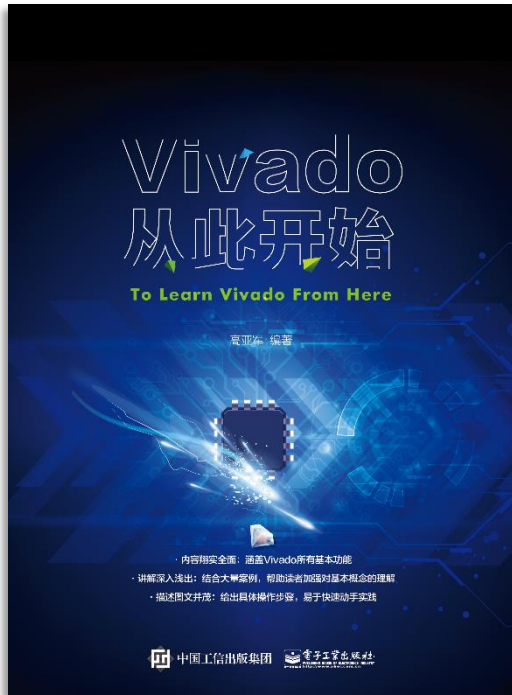


Vivado从此开始 (To Learn Vivado From Here)



本书围绕Vivado四大主题

- 设计流程
- 时序约束
- 时序分析
- Tcl脚本的使用



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- 2012年2月，出版《基于FPGA的数字信号处理（第1版）》
- 2012年9月，发布网络视频课程《Vivado入门与提高》
- 2015年7月，出版《基于FPGA的数字信号处理（第2版）》
- 2016年7月，发布网络视频课程《跟Xilinx SAE学HLS》

- ◆ 内容翔实全面：涵盖Vivado所有基本功能
- ◆ 讲解深入浅出：结合大量案例，帮助读者加强对基本概念的理解
- ◆ 描述图文并茂：给出具体操作步骤，易于快速动手实践



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TCL, Vivado One World

Part 7: Design Flow Management with Tcl in Non Project Mode

Lauren Gao

Non-Project Mode – ASIC Type Flow

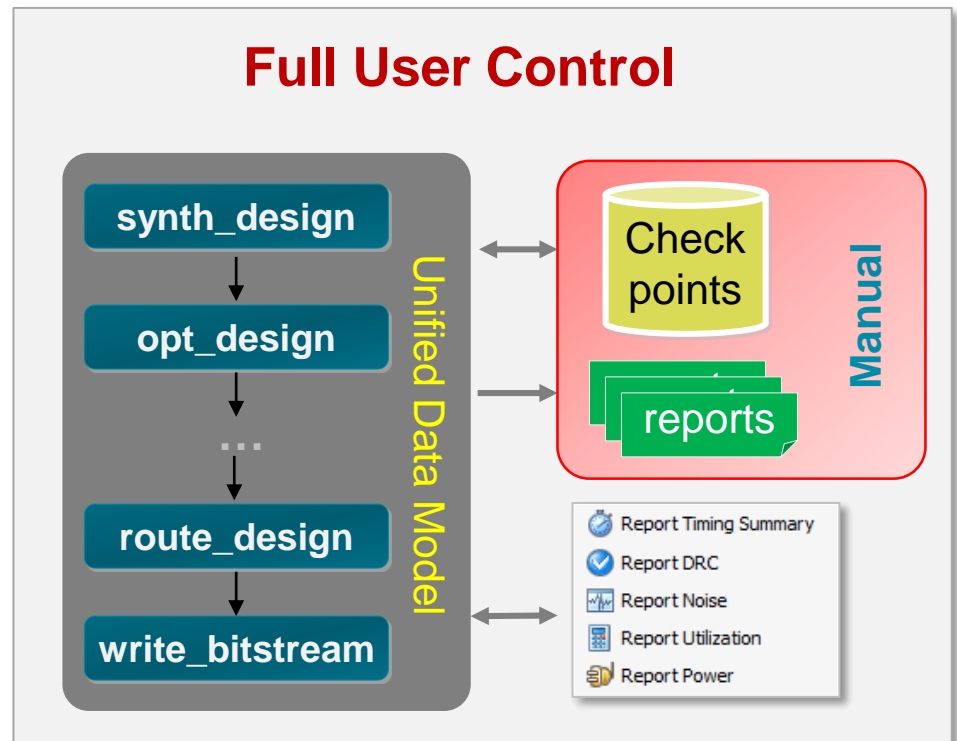
➤ Key advantage – full control over each design flow step

– Full freedom and responsibility to manage a design

- Project status
- HDL sources, constraints, IPs
- Dependency management
- Store results, reports
- Save checkpoints
- No automatic multiple-run support

➤ Flow control

- Synthesis / implementation – Tcl
- Design analysis – Tcl and/or GUI



Preparing Design Files for Vivado Non Project

➤ Four types of design files

- RTL design files
 - VHDL (.vhd), Verilog (.v), System Verilog (.sv)
- XDC files for design constraints
 - .xdc, support both project and module design constraints
- IP files
 - .xci, IPs have been generated by Vivado Manage IP
 - EDIF or NGC files

➤ It's better to create different file folder to store the design files accordingly

src

sim

xdc

IP

Read Design Files into the In-memory Design

➤ Read VHDL files

- `read_vhdl`

➤ Read 3rd party files (EDIF or NGC)

- `read_edif`

➤ Read Verilog files

- `read_verilog`
- For verilog include files

```
set_property FILE_TYPE "Verilog Header" [get_files include.v]  
set_property IS_GLOBAL_INCLUDE true [get_files include.v]
```

➤ Read design constraints files

- `read_xdc`

➤ Read IP files customized by Vivado

- `read_ip`

- All output products associated with the IP core, including the design checkpoint file (DCP) will be read into the in-memory design

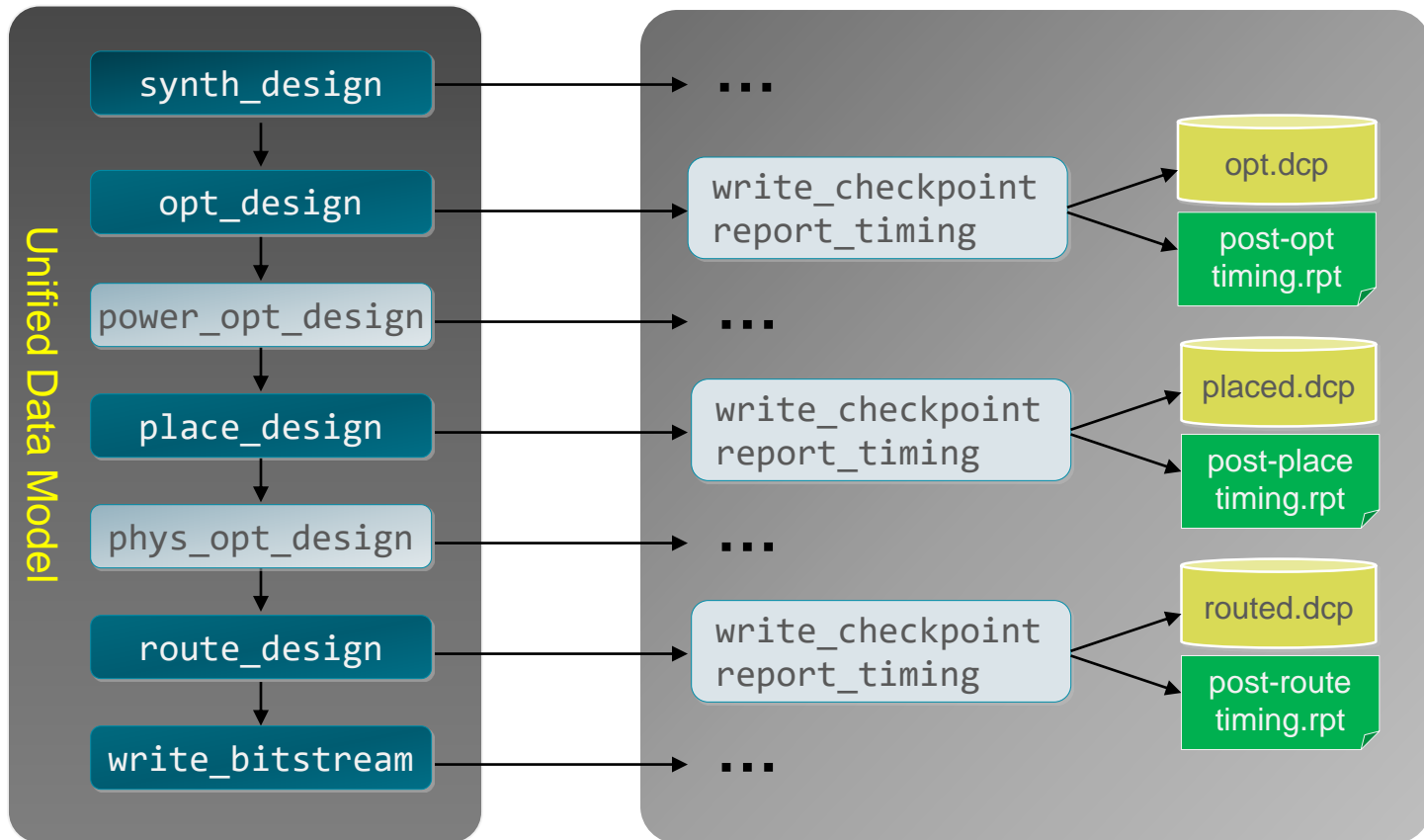
`synth_ip`

`Generate_target`

Scripted Non-Project Flow

Run Tcl flow commands directly from the Vivado IDE Tcl prompt

Manual results and reports management



 optional step

Scripted Non-Project Flow: Example

define variables	<pre>set_property part xc7v485tffbg1157-3 set_property top set synthOptions {-flatten_hierarchy}</pre>
read sources	<pre>read_verilog top.v</pre>
synthesis store results	<pre>synth_design \$synthOptions -top \$top -part \$part write_checkpoint synth.dcp</pre>
optimization placement store results / reporting physical optimization	<pre># Emulate Performance_Explore Strategy opt_design -directive Explore place_design -directive Explore write_checkpoint placed.dcp report_timing -max_paths 100 -file placed.rpt phys_opt_design -directive Explore</pre>
routing store results / reporting	<pre>route_design -directive Explore write_checkpoint routed.dcp report_timing -max_paths 100 -file routed.rpt</pre>
bitstream generation	<pre>write_bitstream bitstream.bit</pre>

Using GUI Design Analysis Features start_gui / stop_gui

```
Command Prompt - vivado -mode tcl

Vivado% place_design
Starting Placer Task
...
Time (s): cpu = 00:00:00 ; elapsed = 00:00:02 .
8 Infos, 0 Warnings, 0 Critical warnings and 0
place_design completed successfully

Vivado% start_gui
```

```
Command Prompt - vivado -mode tcl

Vivado% place_design
Starting Placer Task
...
Time (s): cpu = 00:00:00 ; elapsed = 00:00:02 .
8 Infos, 0 Warnings, 0 Critical warnings and 0
place_design completed successfully

Vivado% start_gui
Vivado% route_design
```

The screenshot shows the Vivado 2013.2 GUI with the Implemented Design tree on the left. The tree includes components like DIVIDER (mydiv8) and MULTIPLIER (mymult8). Three analysis windows are overlaid: Timing (Timing Report), Area (Area Utilization), and Power (Power Summary). The Tcl Console at the bottom shows the commands: Vivado% read_vhdl [glob ../src/*.vhd], Vivado% start_gui, and Vivado% stop_gui. Red boxes and arrows highlight the start_gui and stop_gui commands in the Tcl Console.

Note: You can continue running route_design from GUI (Tcl Console)

Comparing Project and Non-Project Commands

Reference Info

➤ Key flow commands

Project Tcl Commands	Non-Project Tcl Commands
<pre>add_files launch_runs synth_1 wait_on_run synth_1 launch_runs impl_1 wait_on_run impl_1 launch_runs impl_1 - to_step write_bitstream</pre>	<pre>read_<file type> synth_design; write_checkpoint report_utilization opt_design; write_checkpoint power_opt_design; write_checkpoint place_design; write_checkpoint report_utilization phys_opt_design; write_checkpoint route_design; write_checkpoint report_timing_summary report_power; report_drc write_bitstream file.bit</pre>

Some Issues When Using read_ip

Example 1

```
WARNING: [IP_Flow 19-1100] IP 'blk_mem_gen_v7_3_0' does not match the current project part 'xc7vx485tffg1157-1'. You can continue to use existing outputs but part differences may result in undefined behavior. Please review your project settings if this is unexpected."
```

An error will result if the IP in use does not support the xc7vx485tffg1157-1 device.

Example 2

```
"Generating IP 'my_core' ...
```

```
Delivering 'Synthesis' files for IP 'My_core'.
```

```
Error: [Xilinx.com:ip:mig_7series:2.0-0] my_core Target FPGA device"xc7k325t" provided by the mig project did not match with the selected FPGA device 'xc7vx485t' in the project settings. Please cross check the MIG project loader or review the project settings"
```

```
CRITICAL WARNING: [Designutils 20-1365] Unable to generate target(s) for the following file is locked
```

or

```
WARNING: [IP_Flow 19-2162] IP '...' is locked Locked reason: IP '...' is write protected.
```

```
...
```

```
WARNING: [Common 17-259] Unknown Tcl command
```

or

```
ERROR:sim:709 Unable to migrate project
```

```
...
```

```
ERROR: [IP_Flow 19-98] Generation of the IP CORE failed.
```

Solution

```
create_project -in memory
set_property part <part> [current_project]
read_ip <xci file>
set_property is_locked false [get_files <xci file>]
generate_target synthesis [get_files <xci file>]
synth_design -top <top name> -part <part>
```

Demo